Electric Actuator Stepping Motor Compatible Motorless Specification Slider Type (Ball Screw Drive)



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		N				N		

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Ending

ervo motor compatible

EBS

EBK

ETS

ECS

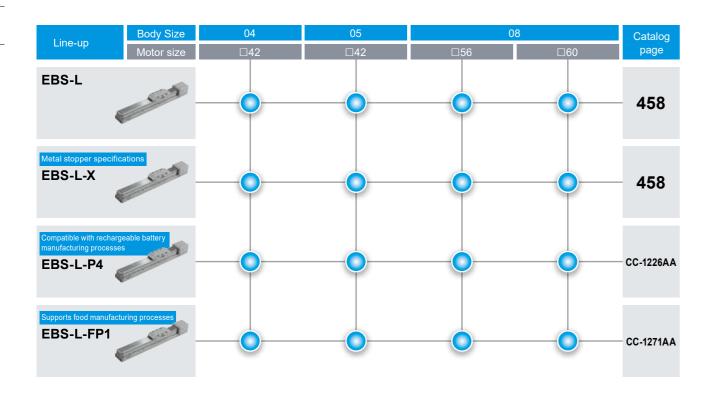
ETS

Slider type (ball screw drive)

Compatible with stepping motor

EBS-L Series





List of supported motor manufacturers * Refer to each model page compatible model and capacity

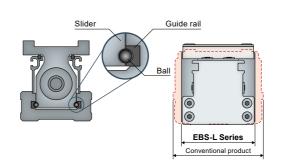
Stepping Motor

CKD

Oriental Motor Co., Ltd. MinebeaMitsumi Incorporated Dyadic Systems Co., Ltd.

Compact, high-rigidity body

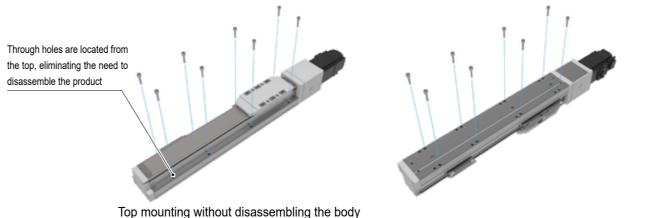
The guide that supports the load uses an outer rail system. The wide guide integrated with the body achieves both high rigidity and space-saving.



	Body	Body Static Allowable Moment						
	Width	MP	MY	MR				
Conventional Product	65 mm	80 N·m	70 N·m	75 N·m 144 N·m				
EBS-05 L	54 mm	103 N·m	103 N·m					
	1	1	1	+				
	11 mm	28 %	47 %	92 %				
	DOWN	UP	UP	UP				

■ Mounting holes provided on top and bottom surfaces

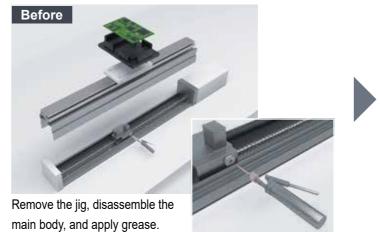
It is a structure that can be installed from both the top and bottom surfaces without disassembling the product. Especially when installing from the top surface, work time can be significantly reduced.



Equipped with external grease fitting port



Grease fitting ports that can be directly greased from the outside are equipped on both sides. Maintenance of the guide and ball screw is possible by greasing from one location without disassembling the main body.





Direct greasing from the outside

Optimal Electric Actuator for More Accurate Homing

EBS-L-X Series (Metal Stopper Specification)

By establishing an accurate zero point based on a mechanical reference, it is possible to perform accurate homing by pushing against the mechanical end.



Optimal electric actuator for rechargeable battery production processes

EBS-L-P4 Series







The use of copper, zinc, nickel-based materials and electrolytic nickel plating is restricted. Grease compatible with ultra-low dew point environments is used, and lubrication of the sliding parts is maintained for long periods, even in dry environments.



EBS-L-FP1 Series



Food-grade (NSF H1) lubricants can be used safely and securely. Contributes to low dust generation by supporting vacuum treatment from the suction port.





System Table

System Table

Servo motor compatible

EBR

ETS

ECS

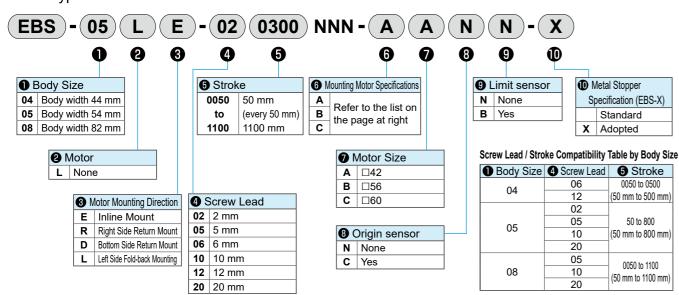
Ending

458

Max. Payload Stroke (mm) and Max. Speed (mm/s) *3 (kg) * Applicable Body Screw Model No. Motor Width Lead Horizontal 100 150 Vertical 400 450 500 550 600 650 700 750 800 850 900 950 1.000 1050 1100 1150 1200 1250 Size (mm) (mm) 300 mm/s EBS-04 L□-06 6 20 5 1.03 sec 1.70 sec 460 42 44 600 EBS-04 L□-12 12 12 2 0.89 sec 0.56 sec 100 90 80 70 60 EBS-05 L□-02 2 10 30 ① 13.34 sec 3.01 sec 6.01 sec (225)(200)(175)(150) 250 Slider Type EBS-05 L□-05 5 10 30 ① 1.23 sec ⑤ 5.35 sec 2.43 sec 42 466 54 500 (450)(400)(350)(300) EBS-05 L□-10 10 5 15 ① 2.70 sec ① 0.65 sec ① 1.25 sec 900 800 700 600 1000 EBS-05 L□-20 20 10 2.5 1.39 sec 0.40 sec 0.70 sec (225)(200)(175)(150)(125)(100)(75)(50) 250 EBS-08 L□-05 5 50 15 2.43 sec 6.02 sec 1.23 sec 22.01 sec 500 (450 (400 (350 (300 (250 (200 (150 (100) __56 EBS-08 L□-10 8 472 82 10 30 ① 3.03 sec ① 0.65 sec 1.25 sec 60 11.01 sec 1000 900 800 700 600 500 400 300 200 EBS-08 L□-20 20 12 2.5 0.40 sec ① 0.70 sec 1.56 sec 5.52 sec *1 The payload when wall mounted is the same as for horizontal installation.

Model Number Configuration

Slider Type



*2 The rated thrust and maximum payload values are the allowable values for the actual thrust and payload may be limited by the motor used by the customer.

*3 The maximum speed is based on the assumption that the customer-mounted motor can output a rotational speed of 3000 rpm. The max. speed is restricted by the stroke. Do not operate at speeds exceeding the limit.

*4 ① shows the Positioning time. This is the case when a specific stroke is operated under horizontal installation, at max. speed, and max. acceleration/deceleration. Please note that this is not the value at max. payload.

Recommended Stepping Motor List

			_	_	_
Code	Manufacturer name	Series	□42	□56	□60
_	A Oriental Motor Co., Ltd.	AZ	AZM46□0□	-	AZM66 <u>0</u> 0 AZM69 <u>0</u> 0
A		AR		ARM46 <u></u> 0	-
В	MinebeaMitsumi Inc.	A17 PM/A23 KM	A17 PM	A23 KM	-
В	Dyadia Systems Co. Ltd.	RMJ	RMJ0411	-	-
С	C Dyadic Systems Co., Ltd.	RMJ	-	RMJ0611, RMJ1211	-

* This product is available only for the actuator (and motor mounting part) and does not include a motor. The motor and driver should be prepared, mounted, and adjusted by the customer.

Ending

EBR

ETS

ECS

CKD

ETS

ECS

EBR

Motor mounting

bolts

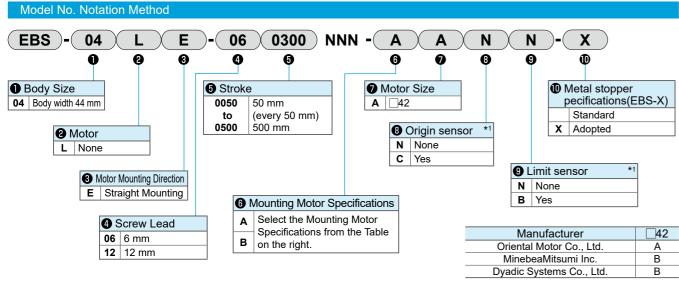
4-M3 x L12

6

3.5 31 5 4-M3 x L12

31





^{*} For motor model Nos., please refer to P. 459.

Specifications

Applicable Motor S	ize	☐42 Stepping motor			
Drive Method		Ball screw ø10			
Stroke	mm	50 to	500		
Screw lead	mm	6	12		
Max. Payload kg	Horizontal	20	12		
*1	Vertical	5	2		
Max. Speed	mm/s	300	600		
Rated thrust *1	N	141	71		
Repeatability	mm	±0.	.01		
Lost Motion mm		0.1 or less			
Static allowable loa	ad N	1030			
Static Allowable Momer	nt N∙m	MP: 62 MY: 62 MR: 92			
Drive part weight	kg	0.3			
Other inertia ko	g·cm²	0.045			
Coefficient of friction	n	0.03			
Mechanical efficien	су	0.8			
Sliding resistance	N	6			
Ball screw length		Stroke	+ 200		
Operating ambient temperature, humid	dity	,	no freezing), no condensation)		
Storage Ambient Temperature, Hum	idity	0 to 40 °C (no freezing), 35 to 80% RH (no condensation)			
Atmosphere		No corrosive gas, ex	cplosive gas, or dust		

used by the customer. Please select the model with your motor.

Stroke and Max. Speed

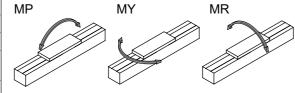
(mm/					
Stroke crew Lead	50 to 500				
6	300				
12	600				

 * The max. speed is the speed when the motor mounted by the customer can output a rotation speed of 3000 rpm. The max. speed is restricted by the stroke. Do not move at speeds beyond the limit.

Allowable Overhang Length

* Refer to P. 480 for details.

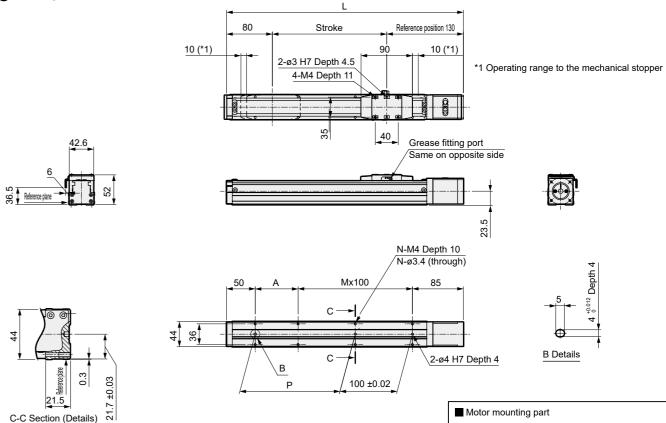
Moment Direction



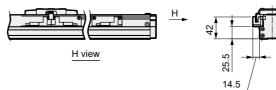
*1 The rated thrust and maximum payload values are the allowable values for the actuator body. The actual thrust and payload may be limited by the motor

External Dimension Drawing Motor Straight Mounting

● EBS-04 LE







* For a stroke of 50 mm, a sensor must be mounted to both sides. Also, sensor dogs are mounted on both sides

Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500
Stroke (mm)	50	100	150	200	250	300	350	400	450	500
L	260	310	360	410	460	510	560	610	660	710
Α	25	75	25	75	25	75	25	75	25	75
M	1	1	2	2	3	3	4	4	5	5
N	6	6	8	8	10	10	12	12	14	14
Р	25	75	125	175	225	275	325	375	425	475
Weight (kg)	1.0	1.1	1.3	1.5	1.7	1.8	2.0	2.2	2.4	2.6

List of Accessories

[Motor mounting parts]

[Motor mounting parts]								
Mounting Motor Chariffontion	Counling	Motor mounting bolt						
Mounting Motor Specification	Coupling	Size Qu						
Α	Chinned attached	М3	4					
В	Shipped attached	М3	4					

[Home Sensor, Limit Sensor]

Sensor							
Manufacturer	Model	Quantity					
OMRON	EE-SX674	3					

4-øD (Threaded hole) (Motor fixing)

D

3.5

Mounting Motor

Specification

CKD

^{*1} Origin sensor and limit sensor are a set. If either is "None," please select "None" for the other as well.

^{*} For sensor specifications, please refer to P. 488.

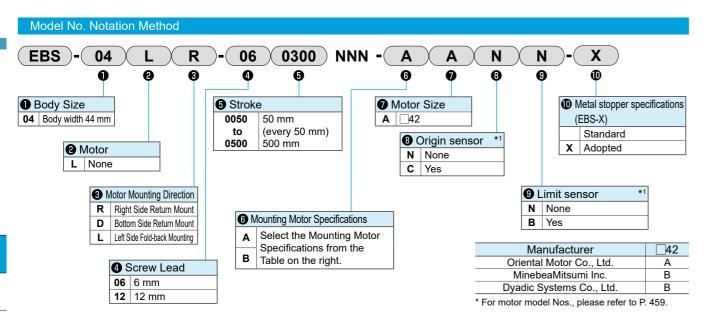
ECS

EBR

Motor Fold-back Mounting Type

Stepping Motor Size : □42





^{*1} Origin sensor and limit sensor are a set. If either is "None," please select "None" for the other as well.

Specifications

Applicable Motor Size		☐42 Stepping motor			
Drive Method		Ball scre	ew ø10		
Stroke	mm	50 to	500		
Screw lead	mm	6	12		
Max. Payload kg	Horizontal	20	12		
*1	Vertical	5	2		
Max. Speed	mm/s	300	600		
Rated thrust *1	Ν	141	71		
Repeatability	mm	±0.	.01		
Lost Motion	mm	0.1 o	0.1 or less		
Static allowable loa	ad N	1030			
Static Allowable Momer	nt N∙m	MP: 62 MY: 62 MR: 92			
Drive part weight	kg	0.	.3		
Other inertia ko	g·cm²	0.0	09		
Coefficient of friction	n	0.0	03		
Mechanical efficien	су	0.	.8		
Sliding resistance	N	6			
Ball screw length		Stroke + 200			
Operating ambient temperature, humid	dity	0 to 40°C (r 35 to 80%RH (n	no freezing), o condensation)		
Storage Ambient Temperature, Hum	idity	-10 to 50°C (no freezing), 35 to 80%RH (no condensation)			
Atmosphere		No corrosive gas, ex	plosive gas, or dust		

^{*1} The rated thrust and maximum payload values are the allowable values for the actuator body. The actual thrust and payload may be limited by the motor used by the customer.

Stroke and Max. Speed

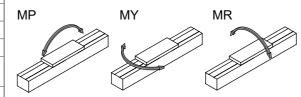
	(11111/3)
Stroke Screw Lead	50 to 500
6	300
12	600

 $^{^{\}star}\,\mbox{The max.}$ speed is the speed when the motor mounted by the customer can output a rotation speed of 3000 rpm. The max. speed is restricted by the stroke. Do not move at speeds beyond the limit.

Allowable Overhang Length

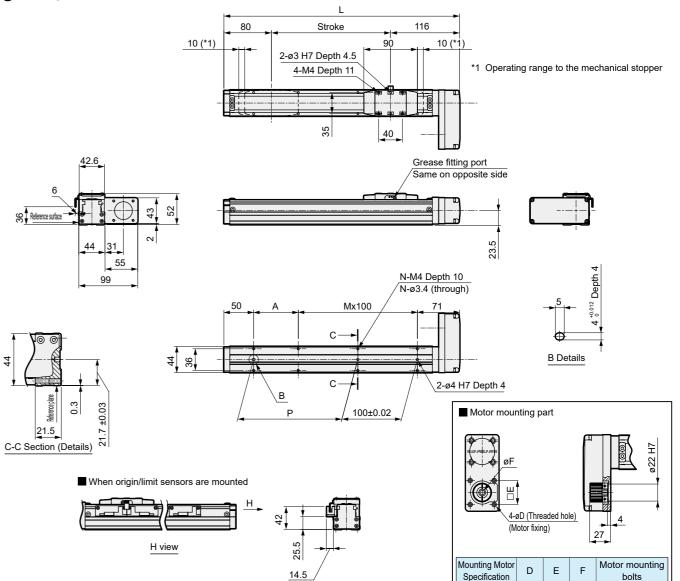
* Refer to P. 480 for details.

Moment Direction



● EBS-04 LR

External Dimension Drawing Motor Right Side Fold-back Mounting



Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500
Stroke (mm)	50	100	150	200	250	300	350	400	450	500
L	246	296	346	396	446	496	546	596	646	696
Α	25	75	25	75	25	75	25	75	25	75
M	1	1	2	2	3	3	4	4	5	5
N	6	6	8	8	10	10	12	12	14	14
Р	25	75	125	175	225	275	325	375	425	475
Weight (kg)	1.0	1.2	1.4	1.7	1.8	1.9	2.1	2.3	2.5	2.7

* For a stroke of 50 mm, a sensor must be mounted to

both sides. Also, sensor dogs are mounted on both

List of Accessories

sides

[Motor mounting parts]

	[Motor mounting parts]						
Maunting Mater Charific	Mounting Motor Chapification	Timing holt pulloy	Motor mounting bolt				
	Mounting Motor Specification	Timing beit, pulley	Size	Quantity			
	Α	Shipped included	М3	4			
	В		М3	4			

	Sensor	
Manufacturer	Model	Quantity
OMRON	EE-SX674	3

3.5 31 6

* For sensor specifications, please refer to P. 488.

CKD

bolts

4-M3 x L12

3.5 | 31 | 5 | 4-M3 x L12

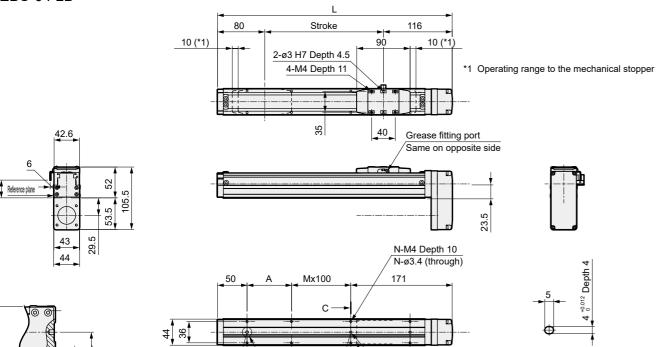
Ending



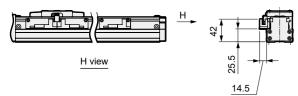
EBR

ETS

ECS



When origin/limit sensors are mounted



* For a stroke of 50 mm, a sensor must be mounted to both sides. Also, sensor dogs are mounted on both sides.

Motor mounting part 4-Dø(Threaded hole) (Motor fixing) Mounting Motor Motor mounting D Ε Specification bolts 3.5 31 6 4-M3 x L12 3.5 31 5 4-M3 x L12

B Details

Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500
Stroke (mm)	50	100	150	200	250	300	350	400	450	500
L	246	296	346	396	446	496	546	596	646	696
Α	25	75	25	75	25	75	25	75	25	75
M	0	0	1	1	2	2	3	3	4	4
N	4	4	6	6	8	8	10	10	12	12
Р	25	75	125	175	225	275	325	375	425	475
Weight (kg)	1.0	1.2	1.4	1.7	1.8	1.9	2.1	2.3	2.5	2.7

List of Accessories

C-C Section (Details)

[Motor mounting parts]

. 31 3				
Mounting Motor Specification	Timing holt pulloy	Motor mounting bolt		
	Timing beit, pulley	Size	Quantity	
Α	01. 1. 1.1	М3	4	
В	Shipped included	М3	4	

[Home Sensor, Limit Sensor]

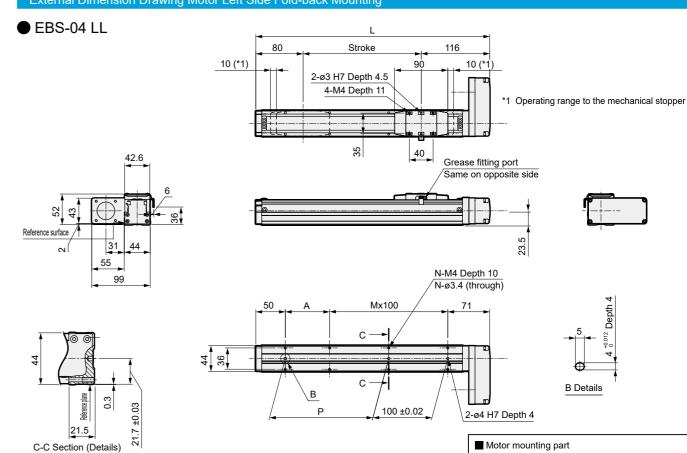
ø4 H7 Depth 4

Motor total length to be within 126 mm

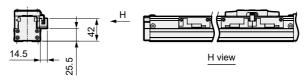
Sensor					
Manufacturer	Model	Quantity			
OMRON	EE-SX674	3			

^{*} For sensor specifications, please refer to P. 488.

External Dimension Drawing Motor Left Side Fold-back Mounting



When origin/limit sensors are mounted



* For a 50 mm stroke, sensors must be mounted on both sides. Also, sensor dogs are mounted on both sides.

4-1 (M	4			
Mounting Motor Specification	D	Е	F	Motor mounting bolts
А	3.5	31	6	4-M3 x L12
В	3.5	31	5	4-M3 x L12

Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500
Stroke (mm)	50	100	150	200	250	300	350	400	450	500
L	246	296	346	396	446	496	546	596	646	696
Α	25	75	25	75	25	75	25	75	25	75
M	1	1	2	2	3	3	4	4	5	5
N	6	6	8	8	10	10	12	12	14	14
Р	25	75	125	175	225	275	325	375	425	475
Weight (kg)	1.0	1.2	1.4	1.7	1.8	1.9	2.1	2.3	2.5	2.7

List of Accessories

iniotor mounting parts]							
Mounting Motor Charification	Timing holt pulloy	Motor mounting bolt					
Mounting Motor Specification	Timing beit, pulley	Size	Quantity				
Α	Shipped included	М3	4				
В		М3	4				

[Home Sensor, Limit Sensor]

	Sensor	
Manufacturer	Model	Quantity
OMRON	EE-SX674	3
* For sonsor specifications	please refer to D 488	

Ending

EBR

ETS

ECS

EBS-05LE

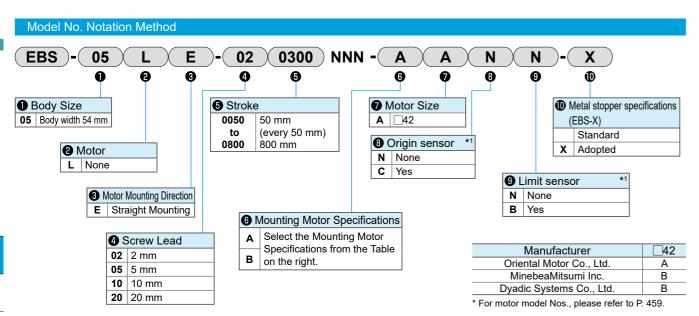
Electric Actuator (Motorless Specification) Slider Type

Motor Straight Mounting Type

● Stepping Motor Size : ☐42



(mm/s)



^{*1} Origin sensor and limit sensor are a set. If either is "None," please select "None" for the other as well.

Specifications

EBR

ETS

ECS

Applicable Motor Size		☐42 Stepping motor					
Drive Method			Ball scr	ew ø12			
Stroke	mm		50 to	008 o			
Screw lead	mm	2	5	10	20		
	Horizontal	30	30	15	10		
*1	Vertical	10	10	5	2.5		
Max. Speed	mm/s	100	250	500	1000		
Rated thrust *1	N	854	341	170	85		
Repeatability	mm		±0	.01			
Lost Motion	mm	0.1 or less					
Static allowable loa	ad N	1168					
Static Allowable Momer	nt N∙m	MP : 103 MY : 103 MR : 144					
Drive part weight	kg	0.7					
Other inertia ko	g·cm²	0.09					
Coefficient of friction	n	0.03					
Mechanical efficien	су	0.8					
Sliding resistance	N	6					
Ball screw length		Stroke + 200					
Operating ambient temperature, humidity		0 to 40°C (no freezing), 35 to 80%RH (no condensation)					
Storage Ambient Temperature, Humidity		-10 to 50°C (no freezing), 35 to 80%RH (no condensation)					
Atmosphere		No corrosive gas, explosive gas, or dust					

^{*1} The rated thrust and maximum payload values are the allowable values for the actuator body. The actual thrust and payload may be limited by the motor used by the customer.

Stroke and Max. Speed

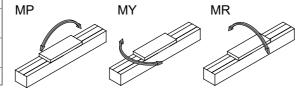
Stroke crew Lead	50 to 600	650	700	750	800
2	100	90	80	70	60
5	250	225	200	175	150
10	500	450	400	350	300
20	1000	900	800	700	600

^{*} The max. speed is the speed when the motor mounted by the customer can output a rotation speed of 3000 rpm. The max. speed is restricted by the stroke. Do not move at speeds beyond the limit.

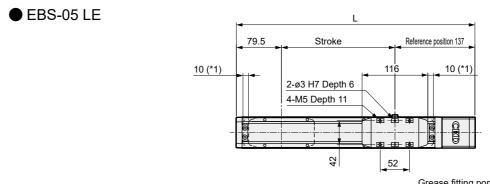
Allowable Overhang Length

* Refer to P. 480 for details.

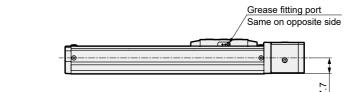
Moment Direction



External Dimension Drawing Motor Straight Mounting

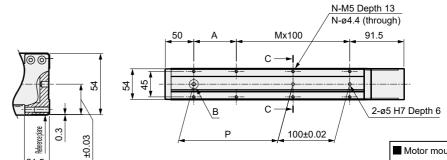


*1 Operating range to the mechanical stopper





B Details



Motor mounting part

23.2

15

2-M2.5

Н	445	
H view	28.5	
or a 50 mm stroke, sensors must be mounted	11_/	

* For a 50 mm stroke, sensors must be mounted on both sides. Also, sensor dogs are mounted on both sides.

When origin/limit sensors are mounted

C-C Section (Details)

Mounting Motor Specification	D	Е	F	Motor mounting bolts
Α	3.5	31	6	4-M3 x L12
В	3.5	31	5	4-M3 x L12

(Motor fixing)

Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500	0550	0600	0650	0700	0750	0800
Stroke (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
L	266.5	316.5	366.5	416.5	466.5	516.5	566.5	616.5	666.5	716.5	766.5	816.5	866.5	916.5	966.5	1016.5
Α	25	75	25	75	25	75	25	75	25	75	25	75	25	75	25	75
M	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8
N	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20
Р	25	75	125	175	225	275	325	375	425	475	525	575	625	675	725	775
Weight (kg)	1.8	1.9	2.1	2.2	2.4	2.5	2.7	2.8	3.0	3.1	3.2	3.4	3.5	3.7	3.8	4.0

List of Accessories

[Motor mounting parts]

[iviolor mounting parts]					
Mounting Motor Specification	Coupling	Motor mounting bolt			
Woulding Wolor Specification	Couping	Size	Quantity		
Α	Shipped attached	М3	4		
В	Shipped attached	М3	4		

[Home Sensor,	Limit Sensor]
---------------	---------------

Manufacturer	Model	Quantity						
OMRON	EE-SX674	3						
* For concer enceifications	* For concer energifications, places refer to D. 400							

* For sensor specifications, please refer to P. 488

Ending

EBR

ETS

ECS

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466

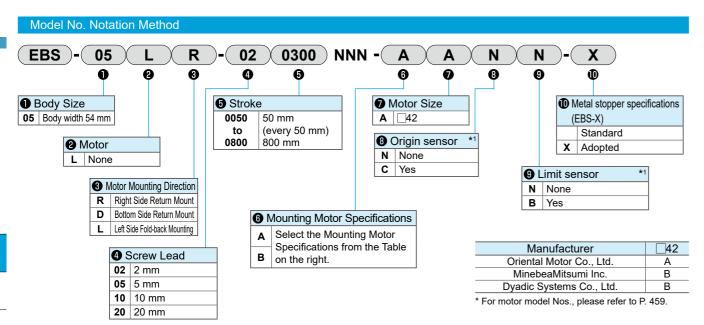
Reverse Parallel Motor Mount Type

Electric Actuator (Motorless Specification) Slider Type

● Stepping Motor Size : ☐42



(mm/s)



^{*1} Origin sensor and limit sensor are a set. If either is "None," please select "None" for the other as well.

Specifications

EBR

ETS

ECS

Applicable Motor S	ize	☐42 Stepping motor					
Drive Method		Ball screw ø12					
Stroke	mm		50 to	800			
Screw Lead		2	5	10	20		
Max. Payload kg	Horizontal	30	30	15	10		
IVIAX. Fayload kg	Vertical	10	10	5	2.5		
Max. Speed	mm/s	100	250	500	1000		
Rated thrust *1	N	854	341	170	85		
Repeatability	mm		±0	.01			
Lost Motion	mm	0.1 or less					
Static allowable loa	ad N	1168					
Static Allowable Mome	nt N·m	MP: 103 MY: 103 MR: 144					
Drive part weight	kg	0.7					
Other inertia ko	g·cm²	0.09					
Coefficient of friction	n	0.03					
Mechanical efficien	су	0.8					
Sliding resistance	Ν	6					
Ball screw length		Stroke + 200					
Operating ambient temperature, humid	0 to 40°C (no freezing), 35 to 80%RH (no condensation)						
Storage Ambient Temperature, Hum	-10 to 50°C (no freezing), 35 to 80%RH (no condensation)						
Atmosphere		No corrosive gas, explosive gas, or dust					

^{*1} The rated thrust and maximum payload values are the allowable values for the actuator body. The actual thrust and payload may be limited by the motor used by the customer. Please select the model with your motor.

Stroke and Max. Speed

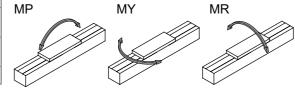
Stroke _ead	50 to 600	650	700	750	800
2	100	90	80	70	60
5	250	225	200	175	150
10	500	450	400	350	300
20	1000	900	800	700	600

^{*} The max. speed is the speed when the motor mounted by the customer can output a rotation speed of 3000 rpm. The max. speed is restricted by the stroke. Do not move at speeds beyond the limit.

Allowable Overhang Length

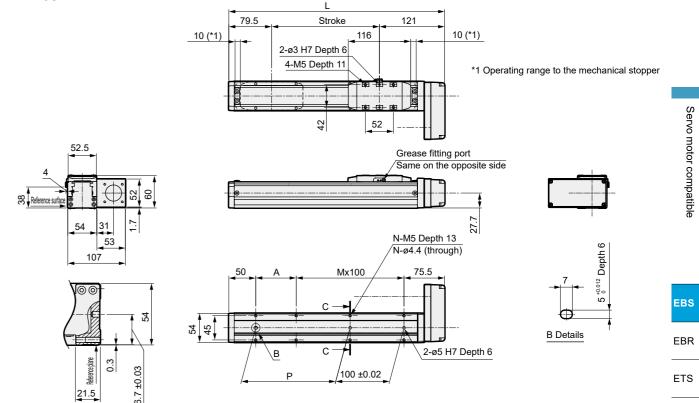
* Refer to P. 480 for details.

Moment Direction



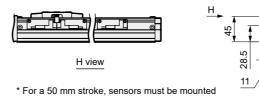
External Dimension Drawing Motor Right Side Fold-back Mounting

● EBS-05 LR





C-C Section (Details)



on both sides. Also, sensor dogs are mounted on both sides

	O (Threa	ided holi	e)	4.5 H 27.5 Z
Mounting Motor Specification	D	Е	F	Motor screw
Α	3.5	31	6	4-M3 x L12
В	3.5	31	5	4-M3 x L12

Motor mounting part

Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500	0550	0600	0650	0700	0750	0800
Stroke (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
L	250.5	300.5	350.5	400.5	450.5	500.5	550.5	600.5	650.5	700.5	750.5	800.5	850.5	900.5	950.5	1000.5
Α	25	75	25	75	25	75	25	75	25	75	25	75	25	75	25	75
M	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8
N	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20
Р	25	75	125	175	225	275	325	375	425	475	525	575	625	675	725	775
Weight (kg)	1.8	2.0	2.1	2.2	2.4	2.5	2.7	2.8	3.0	3.1	3.3	3.4	3.5	3.7	3.8	4.0

List of Accessories

[гою-раск туре]			
Mounting Motor Specification	Timing holt pulloy	Motor mo	unting bolt
Mounting Motor Specification	riming beit, pulley	Size	Quantity
Α	Chinned included	М3	4
В	Shipped included	М3	4

[When home sensor and limit sensor are selected]

Sensor						
Manufacturer	Quantity					
OMRON EE-SX674 3						

* For sensor specifications, please refer to P. 488.

CKD

Ending

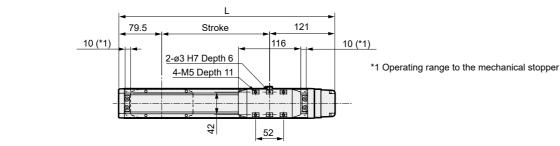
ECS

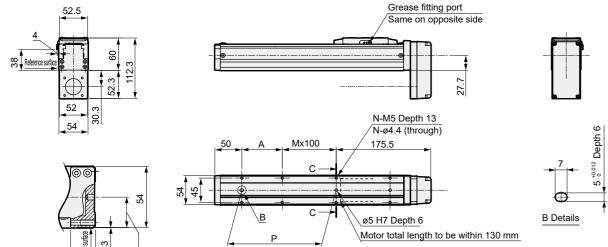
EBS

EBR

ETS

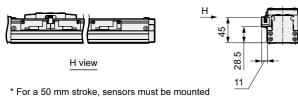
ECS





■ When origin/limit sensors are mounted

C-C Section (Details)



* For a 50 mm stroke, sensors must be mounted on both sides. Also, sensor dogs are mounted on both sides.

	(Tapped			4.5 L 27.5 Z
Mounting Motor Specification	D	Е	F	Motor screw
Α	3.5	31	6	4-M3 x L12
В	3.5	31	5	4-M3 x L12

Motor mounting part

Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500	0550	0600	0650	0700	0750	0800
Stroke (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
L	250.5	300.5	350.5	400.5	450.5	500.5	550.5	600.5	650.5	700.5	750.5	800.5	850.5	900.5	950.5	1000.5
Α	25	75	25	75	25	75	25	75	25	75	25	75	25	75	25	75
M	0	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7
N	4	4	6	6	8	8	10	10	12	12	14	14	16	16	18	18
Р	25	75	125	175	225	275	325	375	425	475	525	575	625	675	725	775
Weight (kg)	1.8	2.0	2.1	2.2	2.4	2.5	2.7	2.8	3.0	3.1	3.3	3.4	3.5	3.7	3.8	4.0

List of Accessories

[Fold-back Type]

[гою-васк туре]							
Mounting Motor Specification	Timing half nullay	Motor mounting bolt					
Mounting Motor Specification	Timing beit, pulley	Size	Quantity				
Α	Chinned included	М3	4				
В	Shipped included	М3	4				

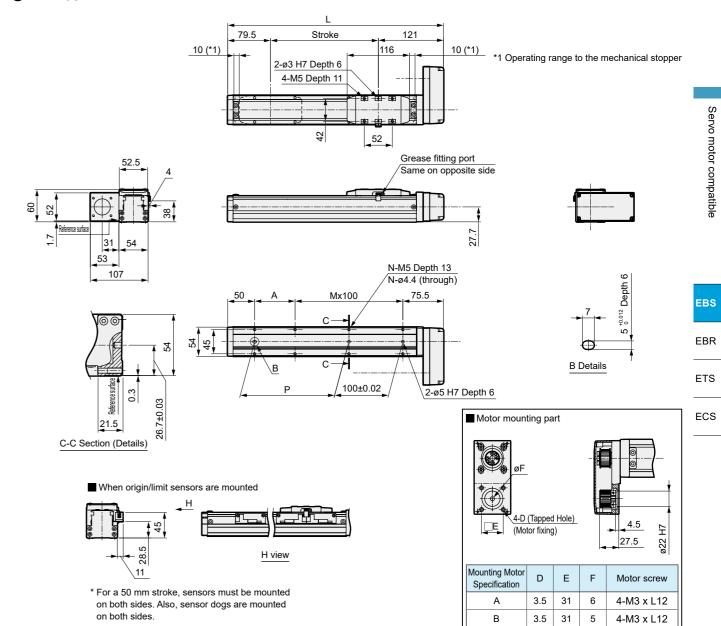
[When home sensor and limit sensor are selected]

Sensor									
Manufacturer Model Quantity									
OMRON EE-SX674 3									

* For sensor specifications, please refer to P. 488.

External Dimension Drawing Motor Left Side Fold-back Mounting

● EBS-05 LL



Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500	0550	0600	0650	0700	0750	0800
Stroke (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
L	250.5	300.5	350.5	400.5	450.5	500.5	550.5	600.5	650.5	700.5	750.5	800.5	850.5	900.5	950.5	1000.5
Α	25	75	25	75	25	75	25	75	25	75	25	75	25	75	25	75
M	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8
N	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20
Р	25	75	125	175	225	275	325	375	425	475	525	575	625	675	725	775
Weight (kg)	1.8	2.0	2.1	2.2	2.4	2.5	2.7	2.8	3.0	3.1	3.3	3.4	3.5	3.7	3.8	4.0

List of Accessories

[Fold-back Type]

[i olu-back Type]			
Mounting Motor Specification	Timing holt pulloy	Motor mou	unting bolt
Mounting Motor Specification	Tilling beit, pulley	Size	Quantity
Α	Shipped included	М3	4
В	Snipped included	М3	4

[When home sensor and limit sensor are selected]

Sensor										
Manufacturer	Model	Quantity								
OMRON	EE-SX674	3								

^{*} For sensor specifications, please refer to P. 488.

CKD

470

Ending

CKD

471

Inline Motor Mount Type

● Stepping Motor Size : □56, □60

Dyadic Systems Co., Ltd.

EBR

ETS

ECS

Applicable Motor S	ize	□56,	☐60 Stepping	Motor				
Drive Method		Ball screw ø16						
Stroke	mm	50 to 1100						
Screw lead	mm	5	10	20				
Max. Payload kg	Horizontal	50	30	12				
*1	Vertical	15	8	2.5				
Max. Speed	mm/s	250	500	1000				
Rated thrust *1	N	683	341	174				
Repeatability	mm		±0.01					
Lost Motion	mm	0.1 or less						
Static allowable loa	ad N		2781					
Static Allowable Momer	nt N∙m	MP: 203 MY: 203 MR: 336						
Drive part weight	kg	1.6						
Other inertia ko	g·cm²	0.24						
Coefficient of friction	n		0.03					
Mechanical efficien	су		0.8					
Sliding resistance	N		20					
Ball screw length			Stroke + 200					
Operating ambient temperature, humid		0 to 40°C (no freezing), 35 to 80%RH (no condensation)						
Storage Ambient Temperature, Hum	idity	-10 to 50°C (no freezing), 35 to 80%RH (no condensation)						
Atmosphere		No corrosive gas, explosive gas, or dust						

*1 The rated thrust and maximum payload values are the allowable values for the actuator body. The actual thrust and payload may be limited by the motor used by the customer. Please select the model with your motor.

Stroke and Max. Speed

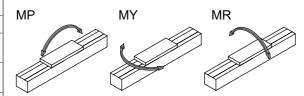
									(111111/3)
Stroke Screw Lead	50 to 700	750	800	850	900	950	1,000	1050	1100
5	250	225	200	175	150	125	100	75	50
10	500	450	400	350	300	250	200	150	100
20	1000	900	800	700	600	500	400	300	200

^{*} The max. speed is the speed when the motor mounted by the customer can output a rotation speed of 3000 rpm. The max. speed is restricted by the stroke. Do not move at speeds beyond the limit.

Allowable Overhang Length

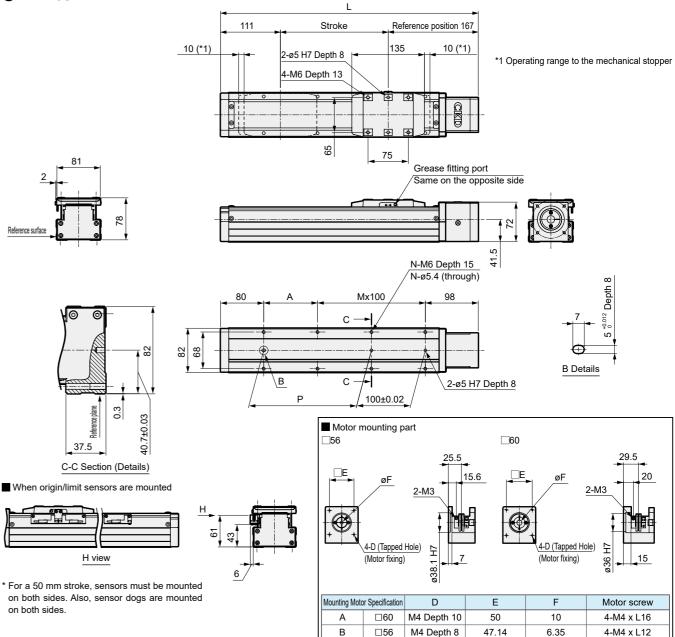
* Refer to P. 480 for details.

Moment Direction



External Dimension Drawing Motor Straight Mounting

● EBS-08 LE



Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500	0550	0600	0650	0700	0750	0800	0850	0900	0950	1,000	1050	1100
Stroke (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1,000	1050	1100
L	328	378	428	478	528	578	628	678	728	778	828	878	928	978	1028	1078	1128	1178	1228	1278	1328	1378
Α	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100
M	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11	11
N	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24	26	26
Р	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1,000	1050	1100
Weight (kg)	4.3	4.6	4.9	5.2	5.6	5.9	6.2	6.6	6.9	7.2	7.5	7.9	8.2	8.5	8.8	9.2	9.5	9.8	10.2	10.5	10.8	11.1

□56

List of Accessories

[Motor mounting parts]

[Motor Mounting parto]						
Mounting Motor Specification	Coupling	Motor mounting bolt				
Mounting Motor Specification	Coupling	Size	Quantity			
Α		M4	4			
В	Shipped attached	M4	4			
С		M4	4			

[Home Sensor, Limit Sensor]

Manufacturer	Model	Quantity
OMRON	EE-SX674	3

* For sensor specifications, please refer to P. 488.

M4 Depth 8

47.14

Ending

EBR

ETS

ECS

Ending

CKD

4-M4 x L12

^{*} Refer to P. 459 for motor model No.

^{*1} Origin sensor and limit sensor are a set. If either is "None," please select "None" for the other as well.

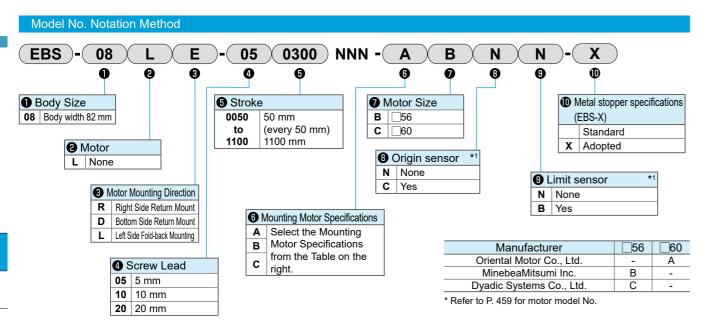
Reverse Parallel Motor Mount Type

Electric Actuator (Motorless Specification) Slider Type

● Stepping Motor Size : □56, □60



(mm/s)



*1 Origin sensor and limit sensor are a set. If either is "None," please select "None" for the other as well.

EBS

EBR

ETS

ECS

Applicable Motor S	ize	□56,	☐60 Stepping	Motor						
Drive Method		Ball screw ø16								
Stroke	mm	50 to 1100								
Screw Lead		5	5 10 20							
Max. Payload kg	Horizontal	50	50 30							
Max. Payload kg	Vertical	15	8	2.5						
Max. Speed	mm/s	250	500	1000						
Rated thrust	N	683	341	174						
Repeatability	mm	±0.01								
Lost Motion	mm	0.1 or less								
Static allowable loa	ad N		2781							
Static Allowable Momer	nt N∙m	MP : 2	03 MY : 203 MF	R: 336						
Drive part weight	kg	1.6								
Other inertia k	g·cm²		0.52							
Coefficient of friction	n		0.03							
Mechanical efficier	су		0.8							
Sliding resistance	N		20							
Ball screw length			Stroke + 200							
Operating ambient temperature, humid		0 to 40°C (no freezing), 35 to 80%RH (no condensation)								
Storage Ambient Temperature, Hum	idity		50°C (no free: %RH (no conde	0//						
Atmosphere		No corrosive	No corrosive gas, explosive gas, or dust							

^{*1} The rated thrust and maximum payload values are the allowable values for the actuator body. The actual thrust and payload may be limited by the motor used by the customer.

Stroke and Max. Speed

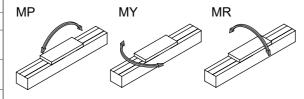
Stroke Lead	50 to 700	750	800	850	900	950	1,000	1050	1100
5	250	225	200	175	150	125	100	75	50
10	500	450	400	350	300	250	200	150	100
20	1000	900	800	700	600	500	400	300	200

^{*} The max. speed is the speed when the motor mounted by the customer can output a rotation speed of 3000 rpm. The max. speed is restricted by the stroke. Do not move at speeds beyond the limit.

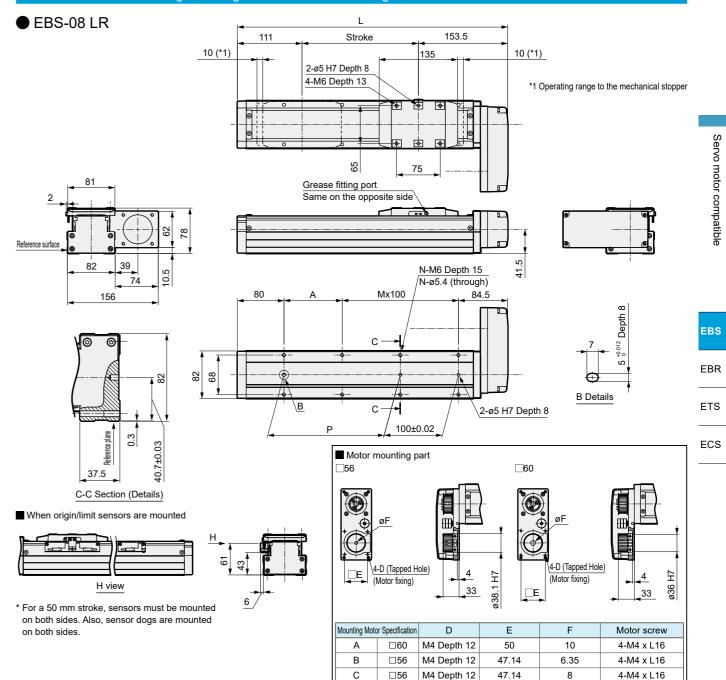
Allowable Overhang Length

* Refer to P. 480 for details.

Moment Direction



External Dimension Drawing Motor Right Side Fold-back Mounting



Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500	0550	0600	0650	0700	0750	0800	0850	0900	0950	1,000	1050	1100
Stroke (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1,000	1050	1100
L	314.5	364.5	414.5	464.5	514.5	564.5	614.5	664.5	714.5	764.5	814.5	864.5	914.5	964.5	1014.5	1064.5	1114.5	1164.5	1214.5	1264.5	1314.5	1364.5
Α	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100
M	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11	11
N	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24	26	26
Р	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1,000	1050	1100
Weight (kg)	4.5	4.8	5.1	5.4	5.8	6.1	6.4	6.8	7.1	7.4	7.7	8.1	8.4	8.7	9.0	9.4	9.7	10.0	10.4	10.7	11.0	11.3

List of Accessories

[Fold-back Type]

[i old-back Type]							
Mounting Motor Specification	Timing holt pulloy	Motor mounting bolt					
Woulding Wold Specification	Tillling beit, pulley	Size	Quantity				
A		M4	4				
В	Shipped included	M4	4				
С		M4	4				

[When home sensor and limit sensor are selected]

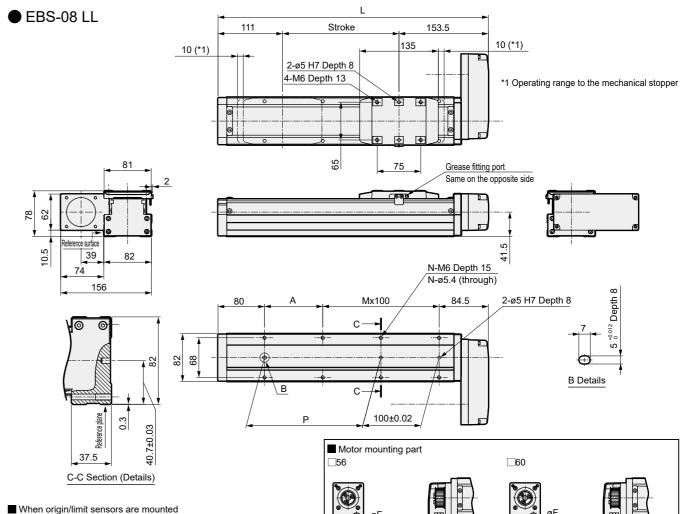
		•	
	Sensor		
Manufacturer	Model	Quantity	
OMRON	EE-SX674	3	

^{*} For sensor specifications, please refer to P. 488.

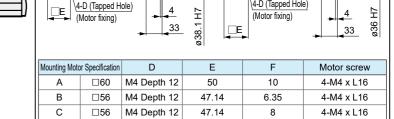
Ending

Ending

CKD



External Dimension Drawing Motor Left Side Fold-back Mounting



4-D (Tapped Hole)

Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500	0550	0600	0650	0700	0750	0800	0850	0900	0950	1,000	1050	1100
Stroke (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1,000	1050	1100
L	314.5	364.5	414.5	464.5	514.5	564.5	614.5	664.5	714.5	764.5	814.5	864.5	914.5	964.5	1014.5	1064.5	1114.5	1164.5	1214.5	1264.5	1314.5	1364.5
Α	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100
M	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11	11
N	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24	26	26
P	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1,000	1050	1100
Weight (kg)	4.5	4.8	5.1	5.4	5.8	6.1	6.4	6.8	7.1	7.4	7.7	8.1	8.4	8.7	9.0	9.4	9.7	10.0	10.4	10.7	11.0	11.3

\4-D (Tapped Hole)

List of Accessories

H view

* For a 50 mm stroke, sensors must be mounted

on both sides. Also, sensor dogs are mounted

[Fold-back Type]

on both sides.

[i old-back Type]			
Mounting Motor Specification	Timing holt pulloy	Motor mo	unting bolt
Mounting Motor Specification	Tillling beit, pulley	Size	Quantity
Α		M4	4
В	Shipped included	M4	4
С		M4	4

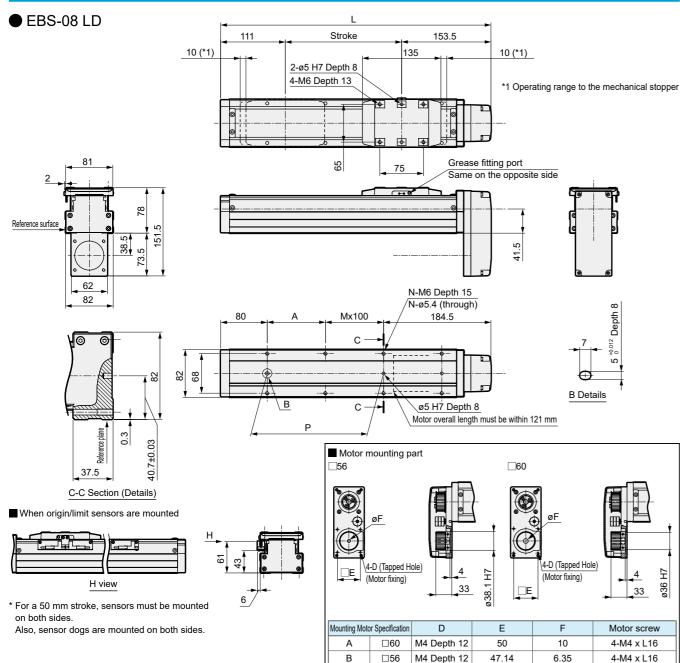
[When home sensor and limit sensor are selected]

	Sensor	
Manufacturer	Model	Quantity
OMRON	EE-SX674	3

* For sensor specifications, please refer to P. 488.

Ending

External Dimension Drawing Motor Bottom Side Fold-back Mounting



Stroke Code	0050	0100	0150	0200	0250	0300	0350	0400	0450	0500	0550	0600	0650	0700	0750	0800	0850	0900	0950	1,000	1050	1100
Stroke (mm)	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1,000	1050	1100
L	314.5	364.5	414.5	464.5	514.5	564.5	614.5	664.5	714.5	764.5	814.5	864.5	914.5	964.5	1014.5	1064.5	1114.5	1164.5	1214.5	1264.5	1314.5	1364.5
Α	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100	50	100
M	0	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10
N	4	4	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24
Р	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1,000	1050	1100
Weight (kg)	4.5	4.8	5.1	5.4	5.8	6.1	6.4	6.8	7.1	7.4	7.7	8.1	8.4	8.7	9.0	9.4	9.7	10.0	10.4	10.7	11.0	11.3

С

□56 M4 Depth 12

List of Accessories

[Fold-back Type]

EBR

ETS

ECS

[
Mounting Motor Specification	Timing holt pulloy	Motor mo	unting bolt
Mounting Motor Specification	Tilling beit, pulley	Size	Quantity
Α		M4	4
В	Shipped included	M4	4
С		M4	4

[When home sensor and limit sensor are selected]

	Sensor	
Manufacturer	Model	Quantity
OMRON	EE-SX674	3

47.14

4-M4 x L16

^{*} For sensor specifications, please refer to P. 488.

EBR

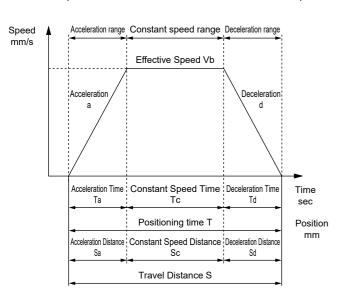
ETS

ECS

Payload varies depending on mounting orientation, screw lead, and motor performance. Select the size and screw lead by referring to the System Table (P. 458) and the specification table for each model. For motor performance, please contact each motor manufacturer. For motor selection, please use the actuator information (mechanical efficiency, etc.) provided in the specifications column.

Confirmation of Positioning Time STEP2

Calculate the positioning time for the selected product according to the example below and check if it meets the required cycle time. Select the speed and acceleration/deceleration from the specification table for each model and the motor selected by the customer.



	Content	Code	Unit	Remarks
en	Set Speed	V	mm/s	
 	Set Acceleration	а	mm/s²	
Setting Value	Set Deceleration	d	mm/s²	
Se	Travel Distance	S	mm	
	Reached Speed	Vmax	mm/s	={2 xaxdxS/(a+d)} ^{1/2}
	Effective Speed	Vb	mm/s	The smaller of V and Vmax
e	Acceleration Time	Та	s	= Vb / a
Calculated Value	Deceleration Time	Td	s	= Vb / d
ated	Constant Speed Time	Tc	s	= Sc / Vb
lonie	Acceleration Distance	Sa	mm	=(axTa ²)/2
S	Deceleration Distance	Sd	mm	=(dxTd ²)/2
	Constant Speed Distance	Sc	mm	= S - (Sa+Sd)
	Positioning Time	Т	s	= Ta+Tc+Td

- * Do not use at speeds exceeding the specifications.
- * Depending on the acceleration/deceleration and stroke, a trapezoidal velocity waveform may not be formed (the set speed may not be reached). In that case, select the smaller of the set speed (V) and the reached speed (Vmax) as the effective speed (Vb).
- * Use at acceleration and deceleration of 1 G or less for horizontal use and 0.5 G or less for vertical use.
- * Settling time varies depending on the usage conditions, but it may take about 0.2 s.
- * 1 G ≈ 9.8 m/s².
- * The customer sets the speed and acceleration/deceleration from the selected motor. For selecting a motor and calculating speed and acceleration/deceleration, please use the actuator information (mechanical efficiency, etc.) provided in the specifications section.

STEP3 **Confirmation of Allowable Overhang Length**

Confirm that the overhang length of the load during operation is within the allowable overhang length (P. 480 to 485).

For details on selection, please check the "Model Selection System" on the CKD website or contact our sales representative.

Introduction to the Model Selection System on our website

[For confirmation via PC]

(https://www.ckd.co.jp/kiki/en/selection_system/)

[For confirmation via iPad or smartphone]



^{*} May not display correctly depending on the smartphone's usage environment.

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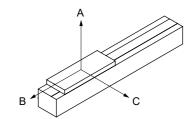
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Allowable Overhang Length (EBS Series)

[Horizontal Installation]



[Allowable Overhang Length]

● EBS-04

Notor Mounting	Acceleration / Deceleration	Screw	Payload	Ove	erhang i	mm
lotor Mounting	G	Lead	kg	Α	В	С
			5	800	160	225
		6	10	570	70	100
	0.3		20	250	30	40
	0.5		4	800	180	210
		12	8	380	80	100
			12	230	50	60
		6	5	800	160	220
			10	400	70	100
Straight	0.5		15	240	40	60
Fold-back	0.5		4	580	180	200
			8	260	80	90
			12	150	50	50
			5	520	160	210
		6	10	240	70	90
	1		15	140	40	50
	ļ		4	350	180	180
		12	8	150	80	80
			12	80	50	40

* The above values are the allowable values for the actuator body, and the actual payload may be limited by the motor used by the customer.

* The value when the actuator's running life is 5,000 km.
(Screw Lead: 2 mm is the value for a travel life of 1,000 km.)

* The overhang direction is a load in a single direction only.

* Dimensions A, B, and C are from the center of the table top surface.

* Stroke: 350 mm, Motor rotation speed: The value at 3,000 rpm.

● EBS-05

Motor Mounting	Acceleration / Deceleration	Screw	Payload	Ove	erhang	mm
Motor Mounting	G	Lead	kg	Α	В	С
			10	1,000	160	225
		2	20	1,000	75	105
			30	815	45	65
			10	1,000	125	170
		5	20	500	55	75
	0.0		30	305	35	45
	0.3		5	1,000	235	285
		10	10	580	110	135
			15	360	70	80
			2.5	1,000	400	385
		20	5	615	195	180
			10	265	90	75
			10	1,000	160	225
		2	20	890	75	105
			30	570	45	65
		5	10	765	125	165
			20	345	55	75
Straight	0.5		30	205	35	45
Fold-back	0.5	5	875	235	280	
		10	10	405	110	125
			15	245	70	75
			2.5	925	400	365
		20	5	425	195	165
			10	180	90	70
			10	1,000	160	220
		2	20	545	75	100
			30	340	45	60
			10	465	125	160
		5	20	200	55	70
	1		30	115	35	40
	'		5	535	235	255
		10	10	240	110	115
			15	140	70	65
			2.5	565	400	315
		20	5	250	190	140
			10	95	85	55

● EBS-08

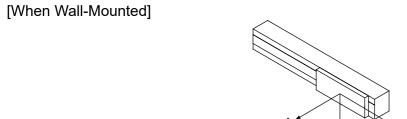
Motor Mounting	Acceleration / Deceleration	Screw	Payload	Overhang mm		
violor iviouriling	G	Lead	kg	Α	В	С
			10	1,000	400	620
		5	25	1,000	150	235
			50	560	65	105
			10	1,000	360	480
	0.3	10	20	840	170	230
			30	530	110	140
			2.5	1,000	1,000	1,000
		20	5	1,000	610	670
			10	950	295	315
	0.5		10	1,000	400	620
		5	25	920	150	235
			50	420	65	105
Straight		20	10	1,000	360	480
			20	625	170	225
Fold-back			30	390	110	140
			2.5	1,000	1,000	1,000
			5	1,000	610	620
			10	670	295	290
			10	1,000	400	600
		5	25	565	150	220
			50	250	65	95
			10	820	360	435
	1	10	20	380	170	200
			30	230	110	120
			2.5	1,000	1,000	1,000
		20	5	870	610	520
			10	400	295	240

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[Allowable Overhang Length]

Allowable Overhang Length (EBS Series)

● EBS-04

Notor Mounting	Acceleration / Deceleration	Screw	Payload	Ove	erhang ı	mm
notor mounting	G	Lead	kg	Α	В	С
			5	180	130	800
		6	10	65	40	470
	0.3		15	25	20	240
	0.3		4	180	150	730
		12	8	60	50	280
			12	25	20	130
			5	180	130	800
		0.5	10	60	40	330
Straight	0.5		15	25	20	170
Fold-back	0.5		4	170	140	520
			8	60	50	200
			12	25	20	90
			5	170	130	490
		6	10	60	40	200
	1		15	25	20	100
	1		4	150	140	320
		12	8	50	50	120
			12	20	20	50

* The above values are the allowable values for the actuator body, and the actual payload may be limited by the motor used by the customer.

* The value when the actuator's running life is 5,000 km.
(Screw Lead: 2 mm is the value for a travel life of 1,000 km.)

* The overhang direction is a load in a single direction only.

* Dimensions A, B, and C are from the center of the table top surface.

* Stroke: 350 mm, Motor rotation speed: The value at 3,000 rpm.

● EBS-05

Motor Mounting	Acceleration / Deceleration	Screw Payload		Overhang mm			
	G	Lead	kg	Α	В	С	
			10	175	125	1,000	
		2	20	55	40	1,000	
			30	15	10	540	
			5	310	230	1,000	
		5	10	125	90	965	
			20	30	20	335	
	0.3		5	245	200	1,000	
		10	10	90	75	460	
			15	40	30	230	
			2.5	350	355	1,000	
		20	5	145	145	500	
			10	45	45	150	
			10	175	125	1,000	
		5	20	55	40	775	
			30	15	10	385	
			5	310	230	1,000	
			10	120	90	685	
Straight			20	30	20	240	
Fold-back	0.5		5	240	200	805	
		10	10	90	75	330	
			15	40	30	160	
			2.5	330	355	855	
		20	5	135	145	355	
			10	40	40	105	
			10	175	125	1,000	
		2	20	55	40	480	
			30	15	10	235	
			5	300	230	955	
		5	10	120	90	425	
	_		20	30	20	145	
	1		5	220	200	500	
		10	10	80	75	200	
			15	35	30	95	
			2.5	290	355	530	
		20	5	115	145	220	
			10	30	40	60	

● EBS-08

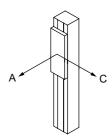
Motor Mounting	Acceleration / Deceleration	Screw	Payload	Ove	erhang i	mm
WOO WOUTHING	G	Lead	kg	Α	В	С
			10	580	370	1,000
		5	25	185	120	1,000
			50	55	35	465
			10	450	325	1,000
	0.3	10	20	190	135	795
			30	100	75	455
			2.5	1,000	1,000	1,000
		20	5	630	565	1,000
			10	280	250	850
			10	580	370	1,000
		5	25	185	120	855
			50	55	35	330
Straight		10	10	445	325	1,000
	0.5		20	185	135	565
Fold-back			30	100	75	325
			2.5	1,000	1,000	1,000
		20	5	585	565	1,000
			10	260	250	605
			10	555	370	1,000
		5	25	180	120	530
			50	50	35	200
			10	405	325	800
	1	10	20	165	135	350
			30	90	70	195
			2.5	1,000	1,000	1,000
		20	5	500	560	845
			10	220	250	370

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[Vertical Installation]



[Allowable Overhang Length]

● EBS-04

4-4 M	Acceleration / Deceleration	Screw	Payload	Ove	erhang ı	mm
Motor Mounting	G	Lead	kg	Α	В	С
			1	800	-	780
		6	3	240	-	230
	0.3		5	120	-	120
		12	1	690	-	630
			1.5	440	-	410
Straight			2	320	-	300
Fold-back			1	800	-	780
		6	3	240	-	230
	0.5		5	120	-	120
	0.5		1	680	-	620
		12	1.5	400	-	440
			2	320	-	290

* The above values are the allowable values for the actuator body, and the actual payload may be limited by the motor used by the customer.

* The value when the actuator's running life is 5,000 km.

(Screw Lead: 2 mm is the value for a travel life of 1,000 km.)

* The overhang direction is a load in a single direction only.

* Dimensions A, B, and C are from the center of the table top surface. * Stroke: 350 mm, Motor rotation speed: The value at 3,000 rpm.

● EBS-05

Motor Mounting	Acceleration / Deceleration	Screw	Payload	Overha	ing mm
Motor Mourting	G	Lead	kg	Α	С
			2.5	640	640
		2	5	295	295
			10	120	120
			2.5	500	490
		5	5	225	225
	0.3		10	85	85
	0.3		1	1,000	1,000
		10	2.5	435	410
			5	195	180
		20	0.5	1,000	1,000
			1	910	760
Straight			2.5	335	280
Fold-back		2	2.5	640	640
			5	295	295
			10	120	120
			2.5	500	500
		5	5	225	225
	0.5		10	85	85
	0.5		1	1,000	1,000
		10	2.5	430	410
			5	190	180
			0.5	1,000	1,000
		20	1	870	740
			2.5	315	275

[Vertical Installation]

Allowable Overhang Length (EBS Series)

● EBS-08

Motor Mounting	Acceleration / Deceleration	Screw	Payload	Overha	ing mm	
Motor Mounting	G	Lead	kg	Α	С	
			5	775	760	
		5	10	360	350	
			15	220	220	
	0.3		3	1,000	1,000	
		10	5	680	630	
			8	405	375	
			0.5	1,000	1,000	
		20	1	1,000	1,000	
Straight			2.5	1,000	930	
Fold-back				5	775	760
		5	10	360	350	
			15	220	220	
			3	1,000	1,000	
	0.5	10	5	670	630	
			8	400	375	
			0.5	1,000	1,000	
		20	1	1,000	1,000	
			2.5	1,000	890	

Ending

Ending

CKD

Servo motor compatible

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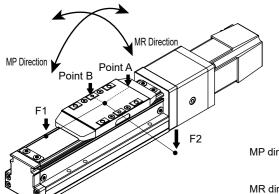
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	(mm)
	Parallelism
	Surface A with respect to Surface B
EBS-04 Series	
EBS-05 Series	0.03
EBS-08 Series	

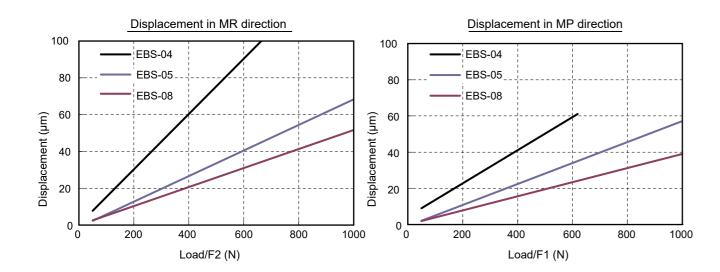
* This is the parallelism when the product is fixed to a

Table Displacement (EBS Series) *Reference Value



MP direction : Displacement at the table end (point A) when a load (F1) is applied at a position 100 mm away from the table center

MR direction : Displacement at the table end (point B) when a load (F2) is applied at a position 100 mm away from the table center



List of Accessories

Motor Mounting Bolts (Common for all motor mounting directions)

Model Number	Mounting Motor Specification	Motor Size	Size	Quantity
EBS 04	A	□42	M3	4
EBS-04	В	□42	M3	4
EBS-05	A	□ 42	M3	4
EB3-03	В		M3	4
	A		M4	4
EBS-08	В	□56 □60	M4	4
	С	_00	M4	4

Coupling

Model Number	Part Name	Quantity
LE (Motor mounting direction: straight)	Coupling (Shipped attached)	1 pc

Timing belt, pulley (motor side)

Model Number	Shipment Form	Quantity
L□ (Motor fold-back mounting)	Shipped included *1	1 pc each

^{*1} The pulley on the main body side is pre-assembled.

Sensor mounting plate

	Model Number	Shipment Form	Quantity
	When sensor "Yes" is selected	Shipped included *1	3 pcs

^{*1} Screws for the mounting plate are also attached. The sensor dog is assembled on all products.

Home Sensor, Limit Sensor

Model Number	Shipment Form	Quantity
When sensor "Yes" is selected	Shipped included *2	3 pcs. *3

^{*2} Screws for sensor mounting are also attached.

Ending

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^{*3} If "None" is selected for either the home sensor or the limit sensor, the other will also be "None."

EBS series Maintenance Parts

Home Sensor, Limit Sensor

[Specifications]

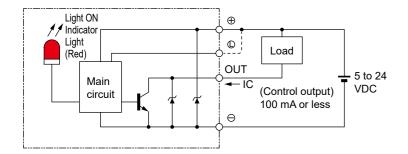
Item		Specifications	
Manufacturer	Manufacturer name	OMRON	
Manuacturer	Model	EE-SX674	
Hysteresis		0.025 mm or less	
Light source (peak e	mission wavelength)	GaAs infrared emitting diode (940 nm)	
Indicator Light		Lights up when light is received (red)	
Power Supply Voltage		5 to 24 VDC ±10 % Ripple (p-p) 10 % or less	
Current Consum	ption	12 mA or less (when L terminal is open)	
	Туре	NPN type (NPN open collector)	
	Output	5 to 24 VDC 100 mA or less	
Control output	Off-state current	0.5 mA or less	
	Residual voltage	0.8 V or less (at 100 mA load current)	
		0.4 V or less (at 40 mA load current)	
Ambient illuminance		Illuminance at Light-Receiving Surface: Fluorescent Lamp: 1,000 lx or less	
Ambient	Operating	-25 to + 55°C, however, no freezing or condensation	
Temperature Range	Storage	-30 to + 80°C, however, no freezing or condensation	
Ambient	Operating	5 to 85 % RH, however, no freezing or condensation	
humidity range	Storage	5 to 95 % RH, however, no freezing or condensation	
Enclosure		IP50 IEC60529 standard	
Cord length		2 m (Connector with cord (EE-1006 2 M))	

Output circuit

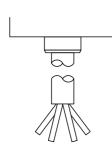
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Wiring Diagram



Terminal arrangement

Brown	5 to 24 VDC
Pink	L
Blue	0 V
Black	OUTPUT

Maintenance Parts

■ Maintenance parts (origin sensor, limit sensor)

Model Number	Applicable Models	Part
EBS-04-SENSOR-N-KIT	EBS-04	Body, cable, mounting plate (1 piece each) *1
EBS-08-SENSOR-N-KIT	EBS-05, EBS-08	Body, cable, mounting plate (1 piece each) *1

^{*1} Screws for mounting plate and sensor are also attached.

■ Maintenance parts (grease nozzle)

Model Number	Applicable Models
EBS-NOZZLE	All models

■ Maintenance parts (steel belt)

Model Number	Applicable Models	
EBS-04-STEELBELT (4-digit stroke code)	EBS-04 (corresponding stroke product)	
EBS-05-STEELBELT (4-digit stroke code)	EBS-05 (corresponding stroke product)	
EBS-08-STEELBELT (4-digit stroke code)	EBS-08 (corresponding stroke product)	

Ending

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■ Do not use in places where dangerous goods such

as ignitable substances, inflammable substances or

Be sure to read this before use.

Common Precautions: Electric Actuator EBS-LE Series

To Use This Product Safely

For general information on Electric Actuators, please refer to Intro 15.

During Design and Selection

This can cause fire or failure.

explosives are present.

■ When mounting the product, be sure to securely hold and fix (including the workpiece) it.

There is a risk of injury due to the product tipping over, falling, or malfunctioning. As a general rule, please fix the product using all mounting holes.

A Warning

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Danger

■ Use within the product's specified operating range.

■ If there is a risk of danger to the human body, install a protective cover.

If the moving parts of the electric actuator page a particular.

If the moving parts of the electric actuator pose a particular danger to the human body, design the structure so that people cannot enter the drive range of the electric actuator or directly touch that area.

- Design a safety circuit or equipment so that damage to equipment, injury to persons, etc., does not occur when the machine stops in the event of a system failure such as emergency stop or power outage.
- Install indoors with low humidity.

 In places exposed to rain or high humidity (80 % humidity or more, with condensation), there is a risk of electric leakage or

fire. Oil drops and oil mist are also strictly prohibited.
Use in such environments can cause damage and malfunction.

■ Make sure that the product is D type grounded (ground resistance of 100Ω or less).

In case of electric leakage, there is a risk of electric shock or malfunction.

■ When installing the actuator in a direction other than horizontal, use a motor with brake.

Without a brake, when the servo is OFF (including emergency stop and alarms) or when the power is OFF, there is a risk of injury or workpiece damage due to the falling of the moving part. ■ When vertically installing the actuator, do everything possible to keep the motor on top.

If the motor is on the lower side, there is no problem in normal operation, but if stopped for a long period, grease may separate and flow into the motor, which may rarely cause a malfunction.

- Do not use this product in a location where the ambient temperature could suddenly change and cause dew to condense.
- Install in a location free from direct sunlight, dust, and corrosive gas/explosive gas/inflammable gas/combustibles, and away from heat sources. In addition, this product has not been considered for chemical resistance.

This can cause failure, explosion, or fire.

- Use and store in locations free from strong electromagnetic waves, ultraviolet rays, or radiation. This can cause malfunction or failure.
- Take possibility of power source breakdown into consideration.

Take measures to prevent injury to people or damage to equipment even if the power source fails.

- Take the operational status into consideration if the machine is reactivated after emergency or abnormal stops. Design so that restarting does not cause harm to people or damage to the equipment. Also, if it is necessary to reset the electric actuator to the starting position, design a safe control device. Consider the possibility of failure of the installed motor. Take measures to prevent injury to personnel or damage to equipment in the event of a power source failure.
- Avoid using this product where vibration and impact are present.
- Do not apply a load to the product that is greater than or equal to the allowable load listed in the materials for selection.
- Use and store in accordance with the working/storage temperatures and where there is no condensation.

(Storage temperature: -10 °C to 50 °C, storage humidity: 35 % to 80 %, Operating temperature: 0 °C to 40 °C, Operating humidity: 35 % to 80 %)

This can cause abnormal product stoppage or reduced service life. If heat accumulates, ventilate.

Caution

- Do not use in a range where the moving table could collide with the stroke end and break.
- Indicate the maintenance conditions in the device's instruction manual.

The functionality of this product may be significantly reduced and safety may not be ensured depending on the usage conditions, environment, and maintenance. If maintenance is performed correctly, the product's functions can be fully utilized

- The product is manufactured in conformity with the related standards. Never disassemble or modify.
- Refer to the instruction manual of the motor mounted to the product and control for your safety before wiring and designing.
- The customer is responsible for confirming the compatibility of CKD products and motors with their systems, machines and equipment.

■ Set up the wiring so as not to apply inductive noise.

Avoid places where large currents or strong magnetic fields are generated.

Do not use the same conduit or wiring (with multi-core cables) as the power lines of large motors other than this product.

Do not use the same conduit/wiring as the inverter power supply or wiring

section used for robots, etc., apply a frame ground to the power supply, and insert a filter at the output section.

■ Do not use this product in an environment where strong magnetic fields are generated.

This can cause malfunction.

■ Be sure to separate the power supply of the output of this product and the power supply of inductive loads that generate surges, such as solenoid valves and relays. If the power supply is shared, surge current may enter the output section and cause damage.

If a separate power supply cannot be used, connect a surgeabsorbing element in parallel directly to all inductive loads.

■ When installing an external stopper or retention mechanism (brake, etc.), place it so as not to affect origin position detection.

The home position is detected when the power is turned on. If the detection operation is obstructed by an external stopper or holding mechanism, there is a risk that an unintended position may be recognized as the home position.

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Ending

For precautions regarding mounting, installation, adjustment, operation, and maintenance, please refer to the CKD Component Product Site(https://www.ckd.co.jp/kiki/en/) \rightarrow 'model No.' \rightarrow Instruction Manual].

MEMO

Customer:

Company Department

Name E-mail

TEL FAX

Please fill out this form and send it to your nearest sales office. We will respond with the model selection results.

Selection Conditions:

Desired Model	EBS-		
Basic Specifications	Max. Stroke :	mm, Ball screw lead :	mm
	Moving stroke :	mm, travel time : s	
Operating Conditions	Set Speed :	mm/s	
Conditions	Set acceleration/deceleration :	mm/s² (set acceleration/deceleration time :	s)
	Repeatability : ±	mm	
		Slider Type	
	Load weight: kg		
	Mounting Orientation: Horizontal / Wall-mounted / Vertical /	Ceiling-mounted / Other	
Load	B C A C B	A C	
Conditions	Distance t	from slider center to load's center of gravity	
	Direction A : mm		
	Direction B: mm		
	Direction C : mm		
	Pressing load :		
	None / Yes (None / Yes (None / When stopped	I)	
	Direction of force on slider center ()	
Operating	Ambient Temperature :	°C, Ambient Humidity :	%
Environment	Atmosphere :		
Mataullaad	Manufacturer : ,	Model No. :	
Motor Used	Motor capacity, size :		
Special Notes			

ETS

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